

# ELI Beamlines CS Status

Pavel Bastl, June 21th. 2016, 30<sup>th</sup> annual TANGO meeting, ONERA, Toulouse



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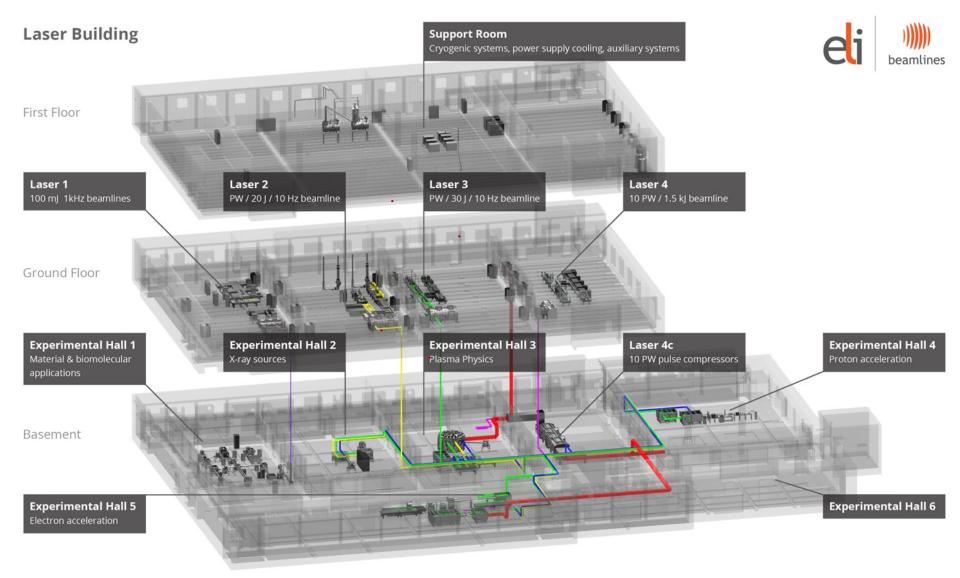






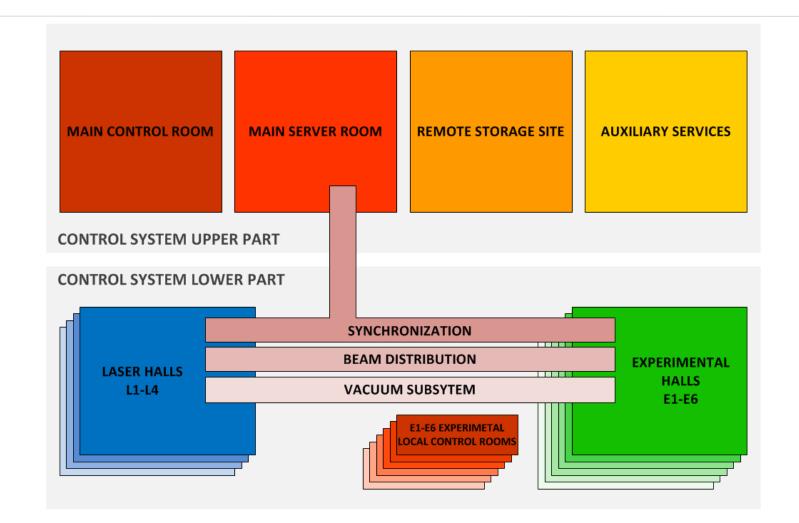


## Central control system perspective





## Control view and subsystems





#### TECHNOLOGY

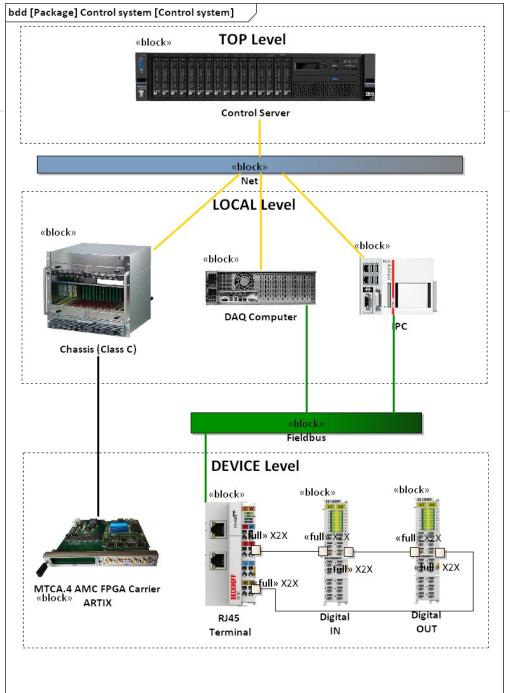
- Vacuum system
- Switch-yard control
- Beam alignment
- Beam diagnostics
- Laser systems interface
- Experiment control
- Instrumentation

#### CONTROL SYSTEM SERVICES

- Control system Hardware (SysML)
  - HW architecture done
  - HW design in progress (Server room, Main control room, Experimental area)
  - HW implementation in progress (Server room, Main control room, Network, Lab)
- Control system Software (UML)
  - SW Architecture in progress
  - SW Design in progress
  - SW Implementation& Testing in progress
  - SW Deployment in progress (testbed)

#### SUPPLEMENTARY SUBSYSTEMS

- Control system network
- Timing system
- Data acquisition
- Safety systems



## Control system structure

#### TOP LEVEL CONTROL

- Standard 2U control servers
- Standard 1U management servers

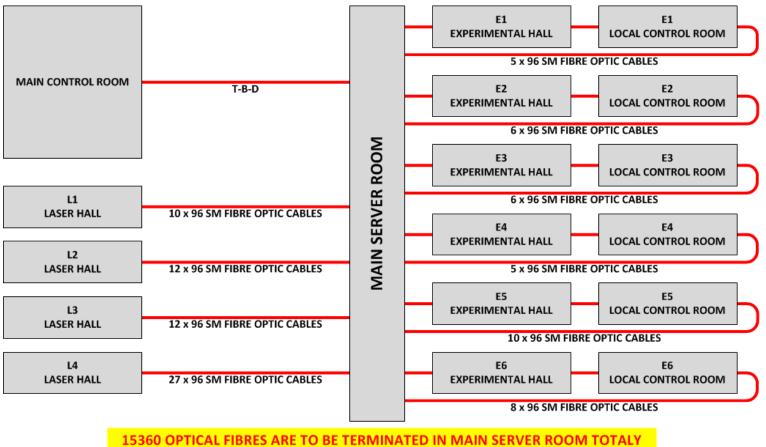
#### LOCAL LEVEL CONTROL

- Micro TCA
- IPC

#### **DEVICE LEVEL**

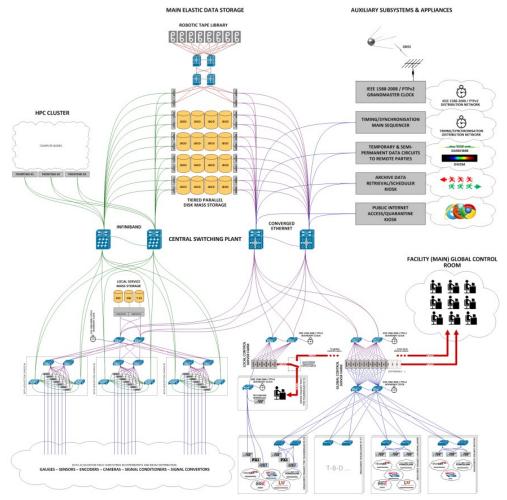
- AMC Cards
- Fieldbus





30+ KM FIBRE OPTICS CABLES ARE TO BE INSTALLED ACROSS THE BUILDING





DATA ACQUISITION SUBSYSTEM

EQUIPMENT CONTROL & PROCESS AUTOMATION SUBSYSTEM







#### **CONVERGED ETHERNET**

- 10-slots 10/40/100G Datacenter Switch
- 42Tb/s Parallel Forwarding Capacity

#### STRUCTURE

- Core switches
- Top of Rack switches
- Bottom of Rack switches
- Access switches





#### LOCAL CONTROL SWITCHES

Control switch - 1U 'cheap' switches

Industrial switch - DIN Rail mount switch







#### **CONTROL SERVERS**

Standard 2U rack servers

- Top level control
- Human interface
- Lenovo x3650 m5 system
- Accessories have to be purchased

#### **MANAGEMENT SERVERS**

Standard 1U rack servers

- Control system hardware management and remote control
- Lenovo x3550 m5 system







#### **CONTROL SERVERS**

#### Standard 2U rack servers

- Top level control
- Human interface
- Lenovo x3650 m5 system
- Accessories have to be purchased







## Control system structure

#### LOCAL LEVEL CONTROL

Micro TCA for advanced control

#### **HIGH-END**

MTCA.4 2x MCH, 12x AMC 9U Crate

#### COMPACT

MTCA.4 2x MCH, 6-9x AMC 2U Crate









#### LOW-END

MTCA.0 1x MCH, 6x AMC 1U Crate





## Control system structure

#### **DEVICE LEVEL**

#### AMC for advanced control

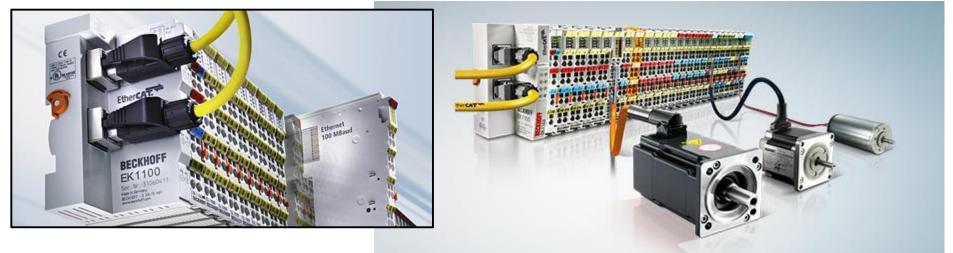
Digitizers, FMC Carriers, etc..

#### **FIELDBUS for Industrial control**

- + Standard Ethernet infrastructure
- + Rich portfolio of IO terminals & Motor control
- + Available with fiber optics for environment with EMC/EMP

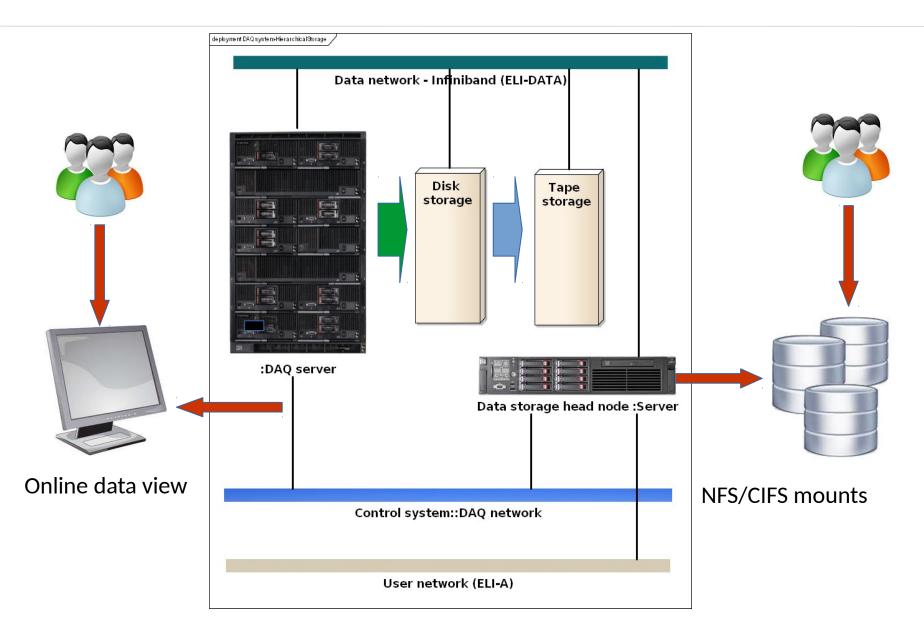
## ETHERNET **POWERLINK**





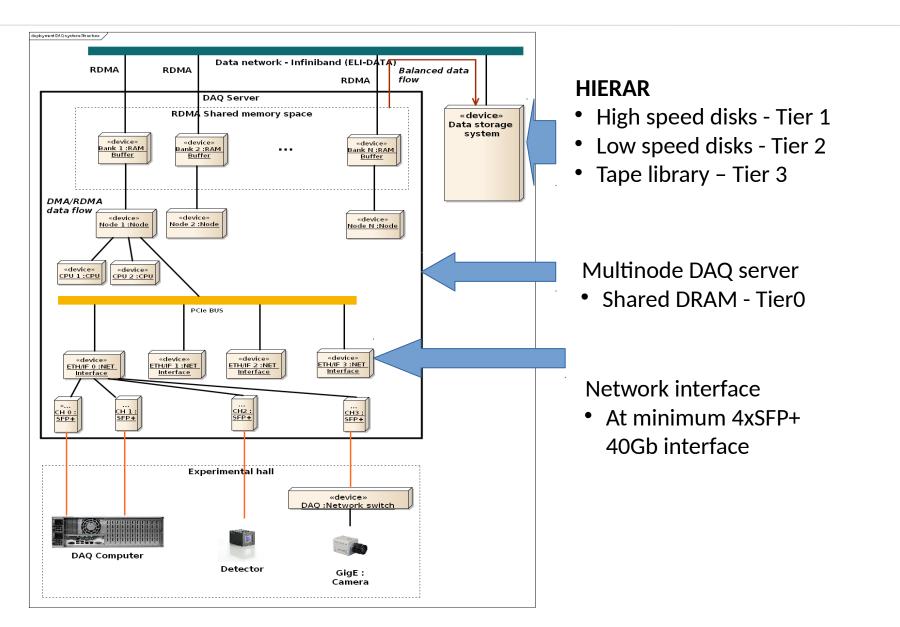


## Data acquisition system





## DAQ server





#### DATA ACQUISTION SERVERS

#### Blade rack servers

- Infiniband switch
- Converged ethernet switch

#### DATA STORAGE

Central multi tier data storage

- Data acquisition
- SSD/HDD/TAPE Tear
- Tier0 Blade server RAM memory
- Extensible solution







## Local Data acquisition hardware

#### DATA ACQUISITION COMPUTERS

#### 4U rack servers

- Local data acquisition
- 11x PCIe x8 slots
- 4x 10Gb Ethernet, RDMA







## Local Data acquisition hardware

#### **DATA ACQUISITION COMPUTERS**

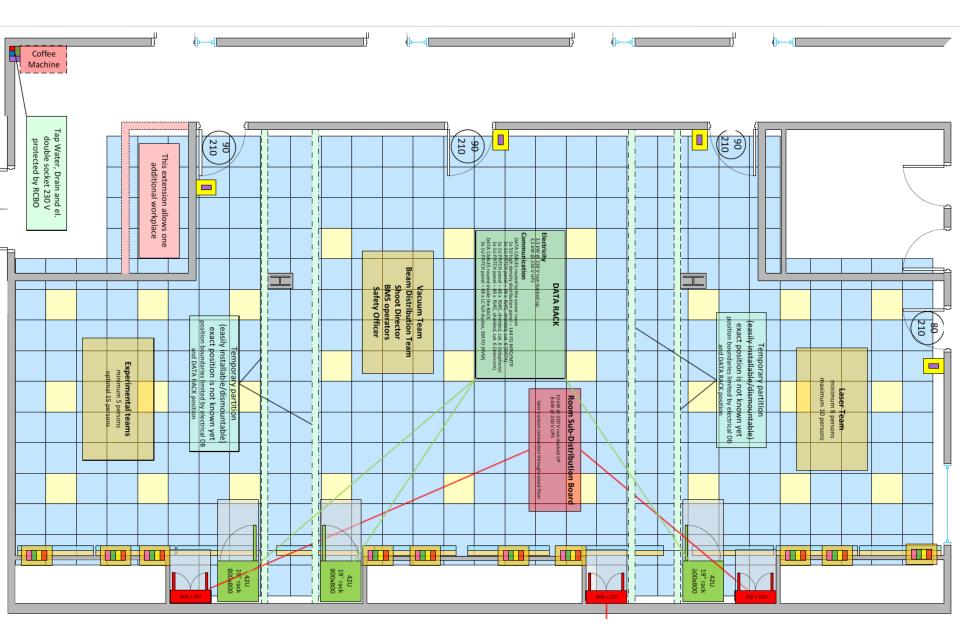
#### uTCA Chassis

- 12 AMC
- PCIe x8 interface to DAQ Computer

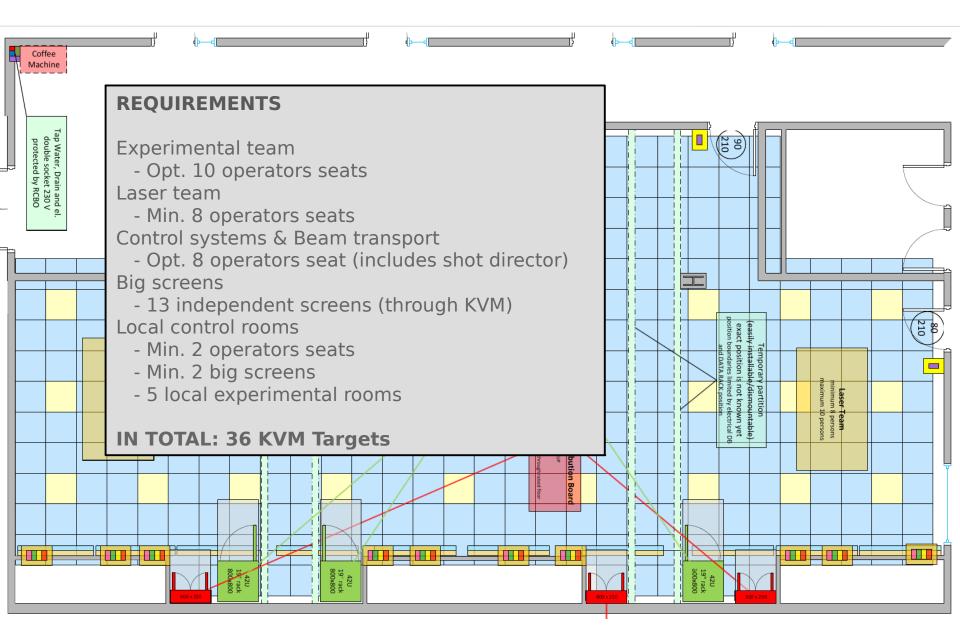










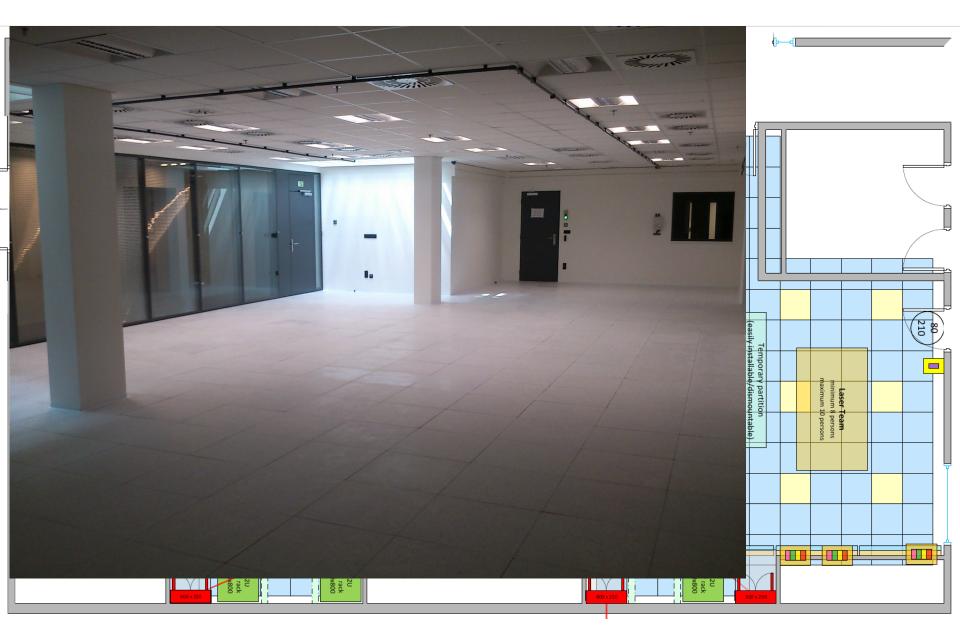




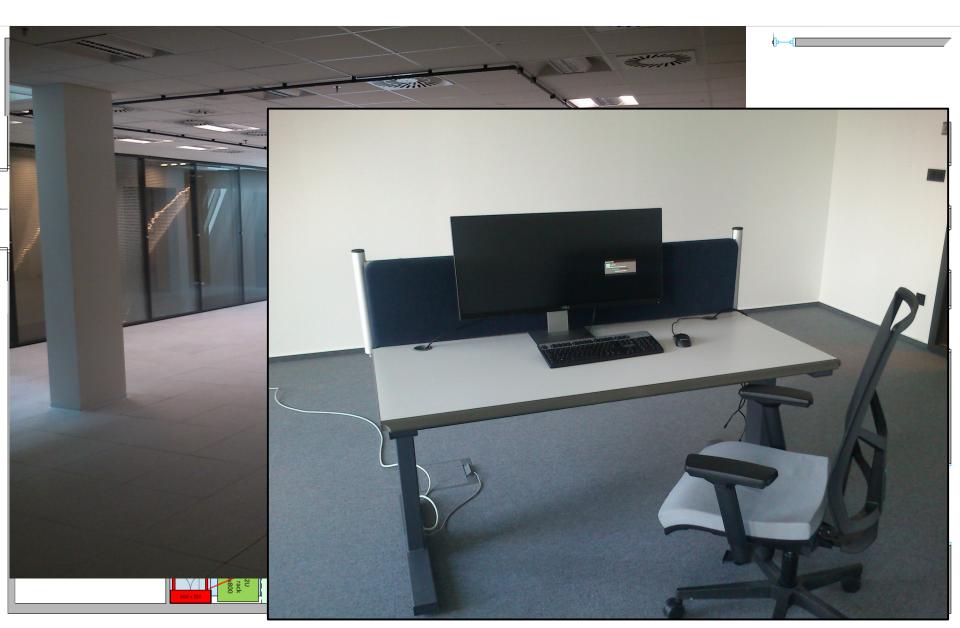






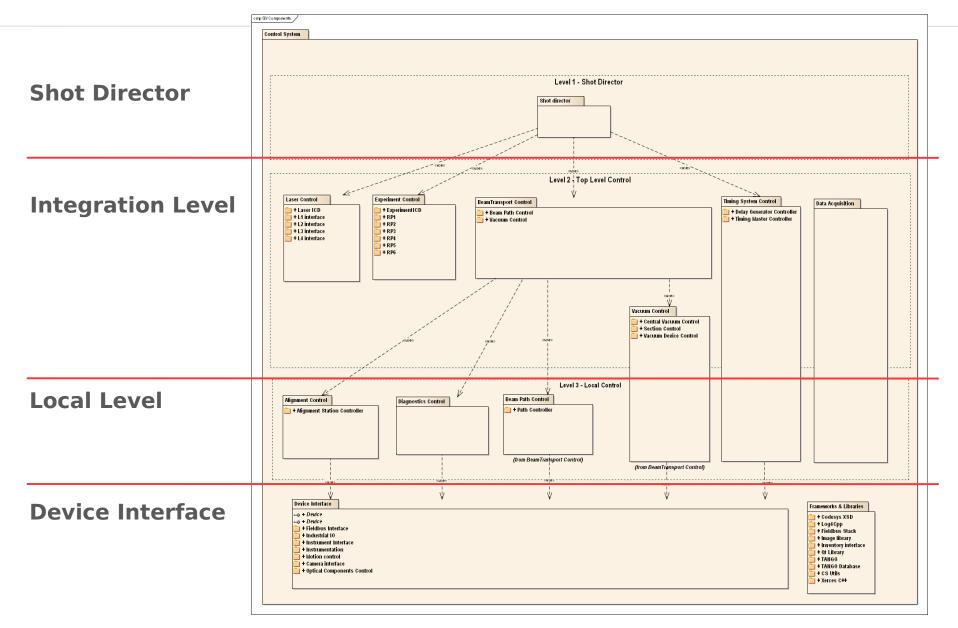








## Control system Software





#### CONTROL SYSTEM SOFTWARE DEVELOPMENT STRATEGIES

Abstract API

Based on user requirements

Component model

C++/Python interface

**TANGO** interface

Matlab (Octave)&Labview&Scilab interface

Component complex configuration by XML

Plugin interface

Device level - lot of devices available on the market

Even more devices will come later

Software generation

Fieldbus software support

Instrumentation

Generic GUI interface

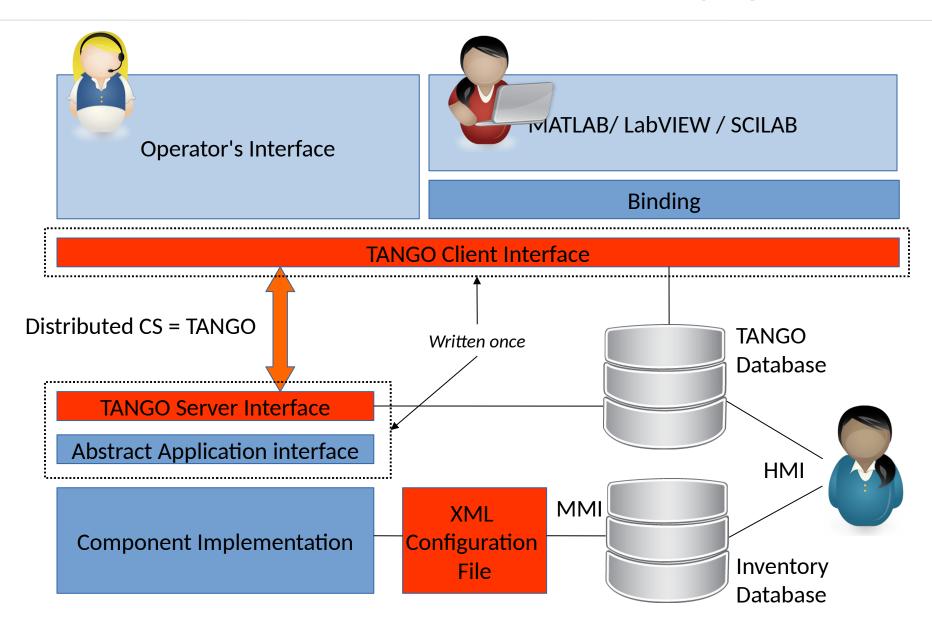
Complex GUI creation without compilation

Automatic software generation support

3D system model support



## Control system Component design structure – TANGO deployment



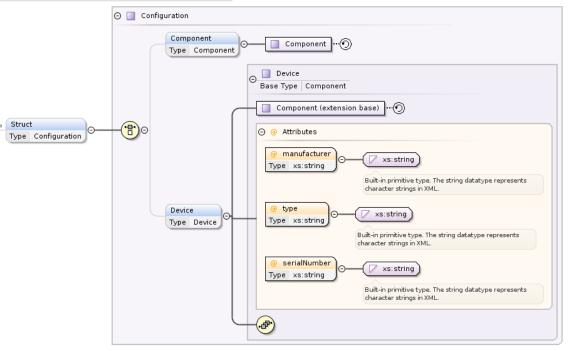


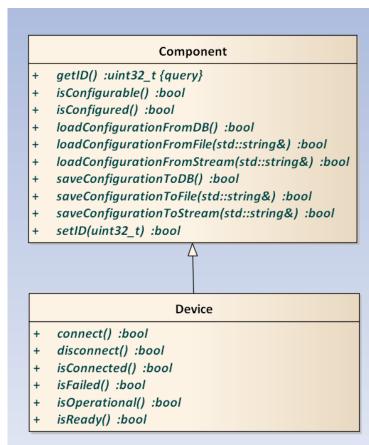
## Control system Software

#### **COMPONENT CONFIGURATION**

#### Reconfigurable components

- Solution for specific parametrization
- Based on XML ser/des technique
  - May be edited by user from XML editor
- May be send/receive through data stream
- May be saved in local file
- May be saved in Database







#### PLUGINS

Plugin

- Reused API

- User component does not have to be even recompiled

- New components or devices which supports well defined API may be added simply Extremely simple API

- Supports version control (automatically taken from plugin source code)

- Supports type checking

template<typename T> class Plugin

public:

{

Plugin();

~Plugin();

```
void attach(const std::string path);
void detach(void);
```

T\* operator->(void) const throw(csexception::CSRuntimeError);

```
uint32_t majorVersion(void);
uint32_t minorVersion(void);
uint32_t patchVersion(void);
```



## Control system Software -Example Cameras

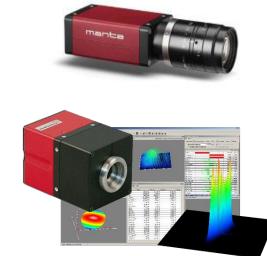
### **STANDARD API DETECTORS**

- Abstract API
- Implementation based on GigE Vision, naturally supported wide range of modern cameras including Wave front sensors
- GigE, GigE2.0, USB 3.0
- CoaxPRESS in development
- Plugin concept gives us the opportunity to work even with obsolete interfaces (USB 2.0) but only in case of specialized detectors
- API IS NOW ADOPTED TO X-Ray cameras just by simple inheritance



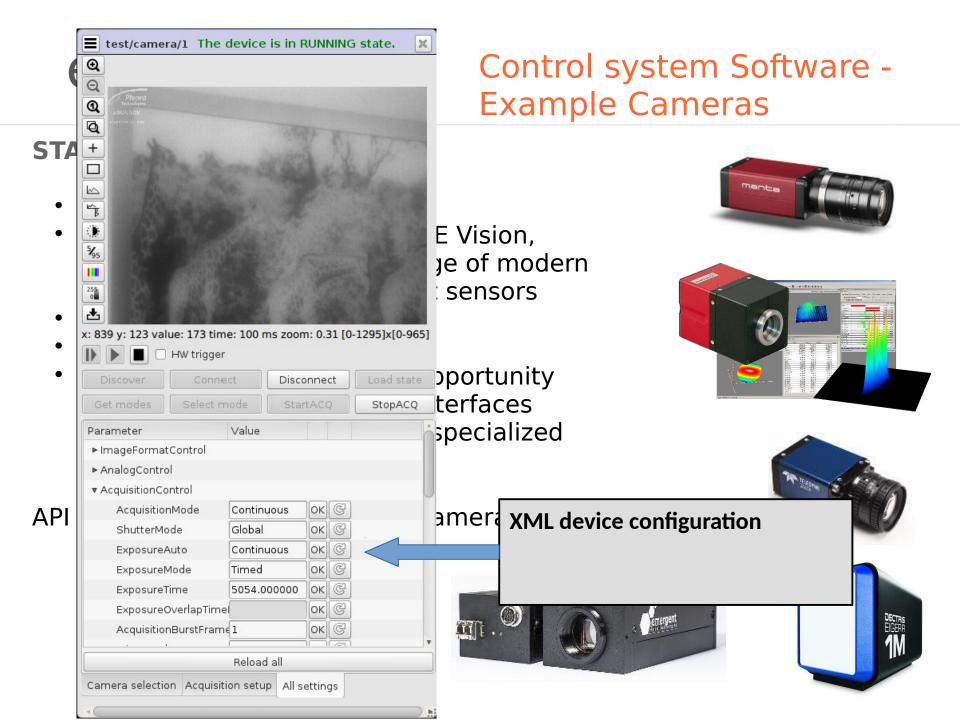










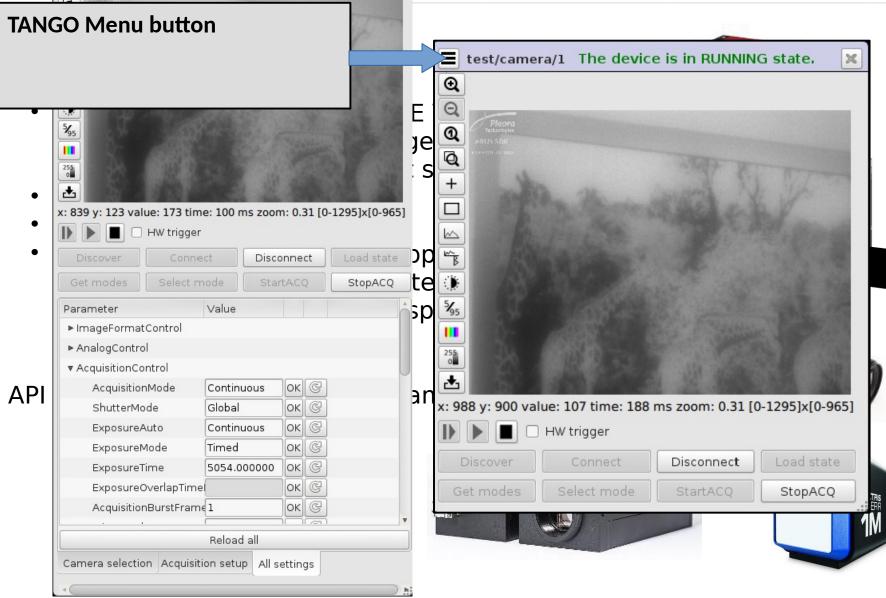


\Xi test/camera/1 The device is in RUNNING state. 🗙

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## Control system Software -Example Cameras





## Control system Software – Example Instrumentation

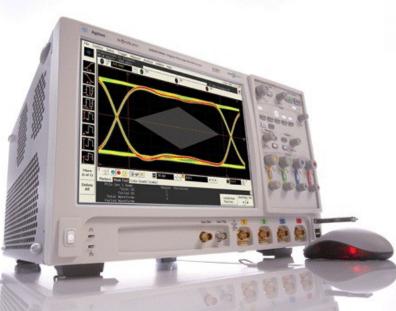
#### **AUTOMATIC SOFTWARE GENERATION**

SCPI Based devices are good example

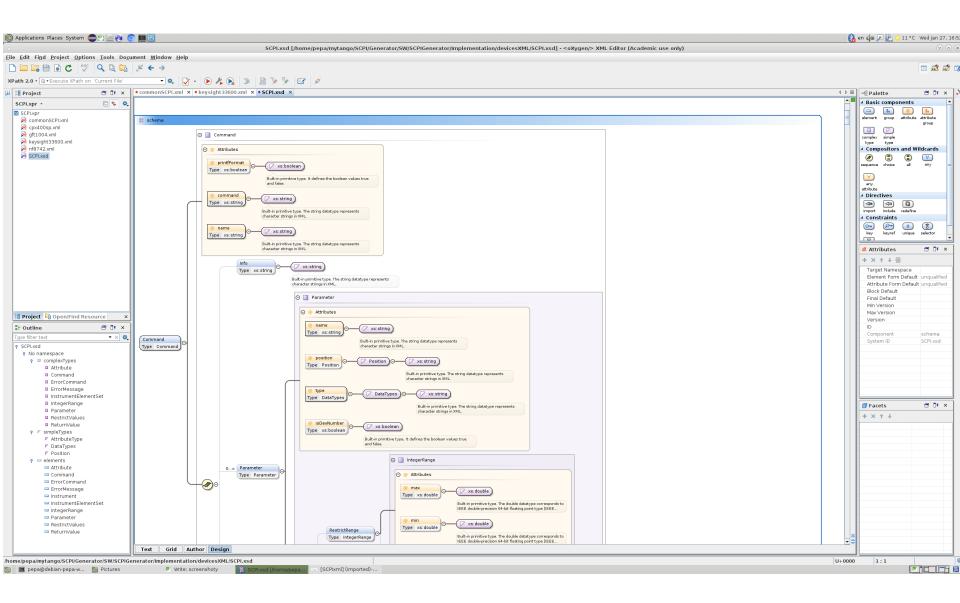
- Motivation → piezo actuator
- Also other devices are support
  - Agilent wave generator
  - Agilent oscilloscopes
  - TTi controlled power sour



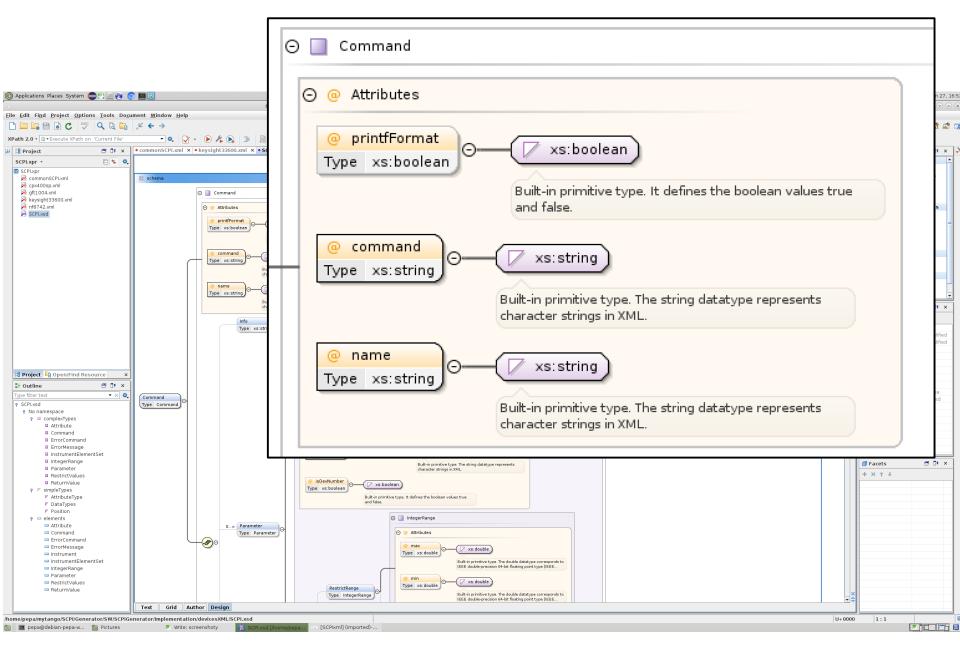








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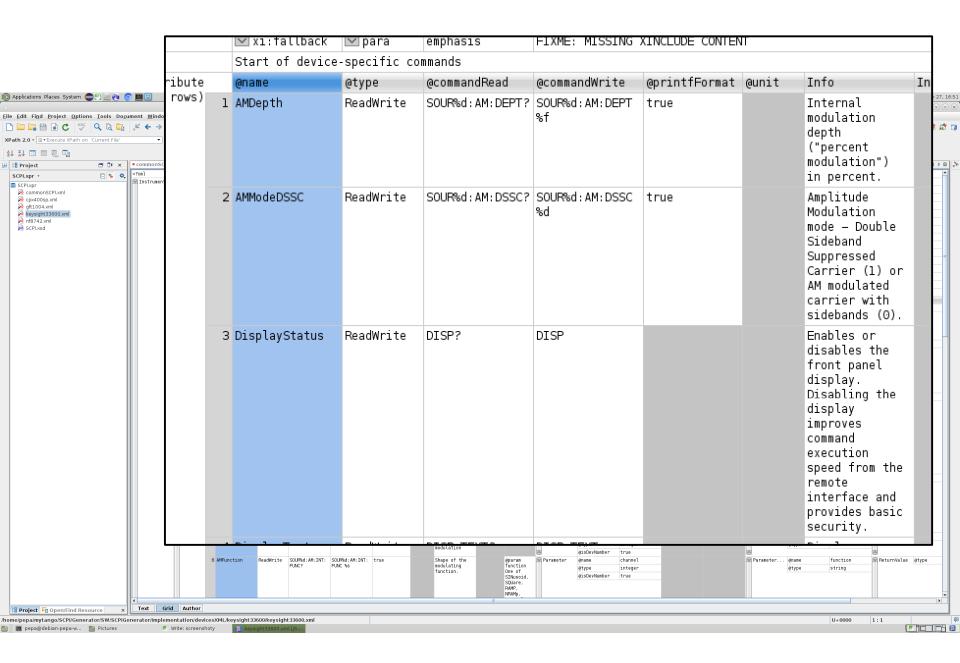
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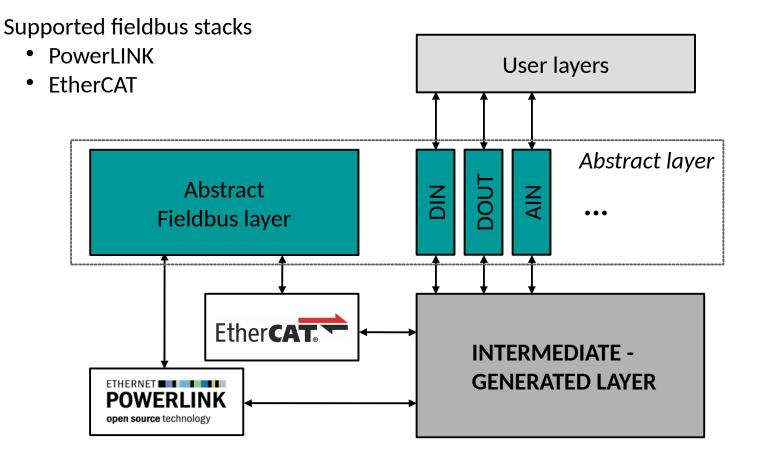
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#### SOFTWARE GENERATION





#### SOFTWARE GENERATION

Software generation chain

- Abstract API upon fieldbus implementation
- Create configuration in supplier provided tool (almost kind of XML file)
- Use abstract API (Industrial IO  $\rightarrow$  iio)
- Generate intermediate C++ code
- Generate GUI components

Supported fieldbus stacks

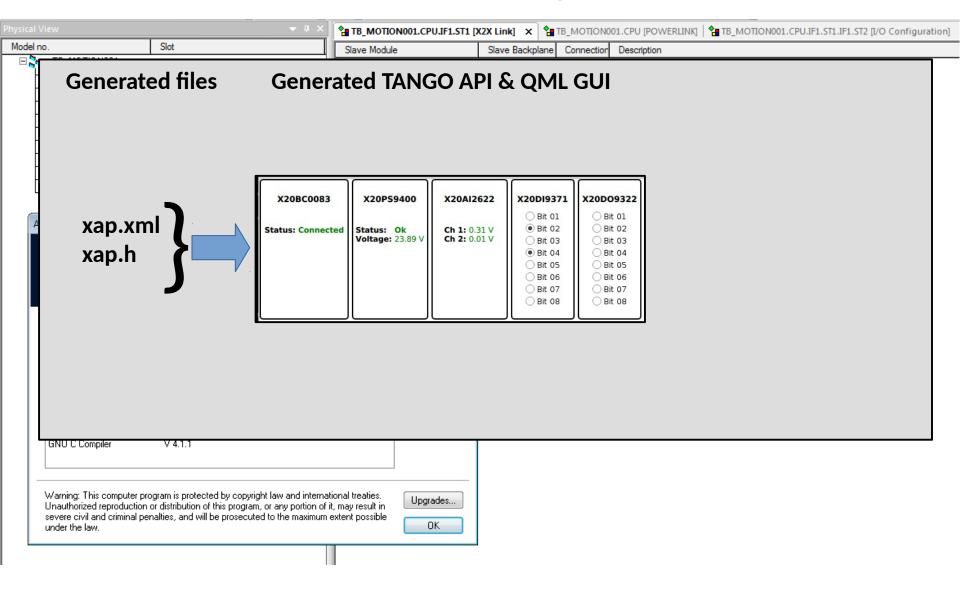
- PowerLINK (B&R Automation)
- EtheCAT (Beckhoff)

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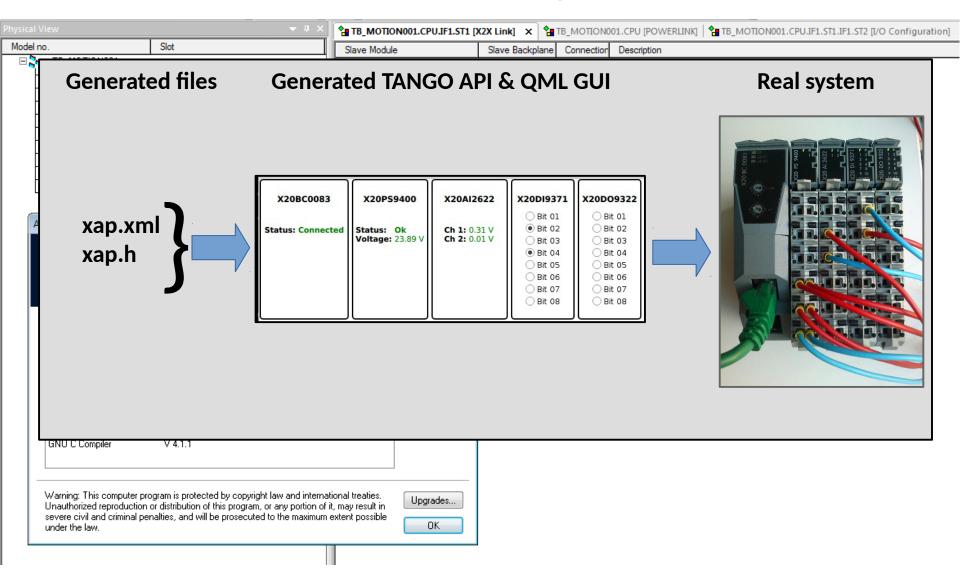


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## Control system Software – Example Frameworks Interfaces

#### STANDARD FRAMEWORKS SUPPORT

Every Component from the lowest layers support frameworks used in research

- Using TANGO  $\rightarrow$  natural support for remote control
- In some cases using standard C++ API for local control when necessary

#### Supported frameworks

- MATLAB
- LabVIEW → LabVIEW TANGO interface is an issue, automatic bridge is under development

All components are supported

- Cameras
- Motion control
- Fieldbus
- ... and more





#### WE ARE OPEN FOR COOPERATION

- Sharing ready to use components, strategies, ideas etc.
- Co-development for higher efficiency
- HW and SW support

COME TO SEE!



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