

Data recording at SOLEIL

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Introduction

Brief status of data recording

- The recording service
 - TangoRecorder
 - RecordingManager
- **Datastorage GUI**

Dataflow usecase





This talk is about recording configuration & metadata recording

We developed early (starting in 2005) a recording service as a set of Tango devices

This service has been rewritten in order to improve performance and simplify its configuration

It is more flexible, open, easy to adapt to various environment

plug-and-play approach for low dependencies between the components





The NeXus/HDF5 file format is the « standard » on most of the beamlines since beginning of operations at SOLEIL (2006)

- > 10 millions files
- Almost all beamlines (24 out of 29) record data using NeXus/HDF5
 - in 15 beamlines: systematically for raw data
 - for 9: depending on the context (acquisition type, instruments, ...)
 - 5 beamlines use their own system to manage experimental data





The data recording is managed using a couple of Tango devices

- RecordingManager: front-end, manage files paths & names,
- TangoRecorder: collects and writes metadata

Additional Tango devices for specific purposes

- ProjectManager: user authentication, project selection, data path locations, files ownership & permissions
- FileTransfer: copy/move files from the beamlines local storage into the central storage

A C++ API (libNexusCPP) on top on HDF5 1.8.x lib

- Used by acquisition devices to record experimental data
- Used by the TangoRecorder



Its role: collect metadata from Tango devices and write it into a location defined by an URI

Few list of commands & attributes

- destinationURI (RW attr)
- The command *RecordDevices* take a list of devices names

Metadata collection is threaded. Recording typically take less than 1 second, even with hundreds of devices (3 seconds in the worse case).





Modular conception to help deployement on another Tango environments

- metadata is written through a interface
- one concrete implementation: SoleilWriter
- plugin mechanism is on the way



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A property (default name is *Recording*) is set to each concerned class/device. It define the attributes to collect and their destinations inside the targeted container.

- The Recording property's content in device instance override the content of Recording property content defined at class level
- It use substitution variables to offer a flexible way to built datasets paths
 - variables may be define through in a TangoRecorder property (next slide)
 - automatic variables : 'device', 'domain', 'family', 'member'
 - some variable can be set in the query part of the URI string (e.g. 'entry')
 - environment variables can be used too (BEAMLINE is define at system level)
- The syntax is: 'data item:target path inside destination'
 - data items are : "strings", attributes names, properties name
 - The target path is decoded and interpreted by the writer object

Recording "\$ (device)" : \$ (entry){entry}/\$ (BEAMLINE){instrument}/\$ (member){detector}/controller_record exposureTime : \$ (entry){entry}/\$ (BEAMLINE){instrument}/\$ (member){detector}/exposure_time nbFrames : \$ (entry){entry}/\$ (BEAMLINE){instrument}/\$ (member){detector}/nb_frames binningH : \$ (entry){entry}/\$ (BEAMLINE){instrument}/\$ (member){detector}/binning_x binningV : \$ (entry){entry}/\$ (BEAMLINE){instrument}/\$ (member){detector}/binning_y latencyTime : \$ (entry){entry}/\$ (BEAMLINE){instrument}/\$ (member){detector}/gap_time

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One can define as many variables as needed to shorten destination paths

```
# General destination paths inside the Nexus tree
entry_grp = /$(entry) {entry}
instrument = $(entry_grp)/$(BEAMLINE) {instrument}
```

```
# Final group name definition
device_names = $(domain)-$(family)-$(member)
device_name_or_alias = $(alias|device_names)
device group name = $(specific group name|device name or alias)
```

```
# Final default group path for a device
device_instr_grp = $(instrument)/$(device_group_name)
```

```
# Paths related to device classes to put in the NXinstrument group
detector = $(device_instr_grp){detector}
bender = $(device_instr_grp){bender}
beam = $(device_instr_grp){beam}
diffractometer = $(device_instr_grp){diffractometer}
```

\$(a|b) means : if 'a' is defined then substitute the value of 'a', otherwise substitute 'b'

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Using the additional substitution variables the previous recording configuration for LimaDetector device class is:

Recording	"\$(device)" : \$(detector)/controller_record
	exposureTime : \$(detector)/exposure_time
	nbFrames : \$(detector)/nb_frames
	binningH : \$(detector)/binning_x
	binningV : \$(detector)/binning_v
	latencyTime : \$(detector)/gap_time

Each time the TangoRecorder is asked to record metadata for a device, it read the 'Recording' property attached to both the device and its class





Manage the data recording (experimental data & metadata). It is the entry point.

High level commands

Dynamic interface

 Attributes for file name, data path, entry name (if using NeXus), intermediate path (if using a temporary storage),...

Automatic values

 Numeric counters, date/time values, attributes values of other devices can be used to build paths strings

Hook mechanism

 Allow to trigger actions on other devices at some key moments (start, end, new file)





Dynamic interface definition ('Variables' property)

Each line defines a attribute

- a short name that can be used in another dynamic field and to define the 'destinationURI' attribute value
- the attribute name and label
- some properties (RO/RW, operator/expert level, lock at start)
- optionaly a data source (a tango attribute value of another device)
- optionaly a default value

```
# user defined sub directory, file name and nxentry name
sdir@dataSubDirectory:Data subdirectory path:(O,L)
fn@fileName:File name:(O,L)
nx@rootNode:Root node:(O,L)
```

Values available from the ProjectManager device (read-only)
rp@rootPath:Root path:storage/management/projectmanager.1/rootPath:(0)
uid@projectUid:Project UID:storage/management/projectmanager.1/projectUID:(0)
gid@projectGid:Project GID:storage/management/projectmanager.1/projectGID:(0)
pc@projectCode:Project code:storage/management/projectmanager.1/currentProject:(0)

```
# spool paths definitions
spp@spoolProjectPath:Spool project path:(0,R):/nfs/srv5/spool1/tangorecorder/[pc]
```

Final destination in the storage facility
stp@storageDestPath:Storage destination path:(O,R):[rp]/[pc]/[sdir]
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Destination paths and names is defined using a URI ('destinationURI' RO attribute) according to a specific pattern (defined by a property named 'URIpattern').

file:[spp]/[sdir]/[fn].nxs?entry=[nx],uid=[uid],gid=[gid], file_mode=640,dir_mode=755,dev_config=[_dc_],dest_path=[stp]

user defined sub directory, file name and nxentry name
sdir@dataSubDirectory:Data subdirectory path:(O,L)
fn@fileName:File name:(O,L)
nx@rootNode:Root node:(O,L)

Values available from the ProjectManager device (read-only)
rp@rootPath:Root path:storage/management/projectmanager.1/rootPath:(0)
uid@projectUid:Project UID:storage/management/projectmanager.1/projectUID:(0)
gid@projectGid:Project GID:storage/management/projectmanager.1/projectGID:(0)
pc@projectCode:Project code:storage/management/projectmanager.1/currentProject:(0)

spool paths definitions
spp@spoolProjectPath:Spool project path:(O,R):/nfs/srv5/spool1/tangorecorder/[pc]

Final destination in the storage facility
stp@storageDestPath:Storage destination path:(O,R):[rp]/[pc]/[sdir]

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RecordingManager

According to the previously defined dynamic interface...

The 'destinationURI' attribute (expert level) therefore is:

file:/nfs/srv5/spool1/tangorecorder/com-swing/subfolder/data_file_0016.nxs?
entry=scan,uid=100211,gid=10021,file_mode=640,dir_mode=755,dev_config=,
dest path=/nfs/ruche-swing/swing-solei1/com-swing/subfolder

storage/management/recording	manager.1	
Ready.		
Recording Session Counter	16 No unit	
File Counter	1 No unit	
User Counter	17 No unit	
Current Config	<not memorized=""></not>	
Run Cycle	2019/5	
Start Time	n/a	
Current Time	2019-05-29T15:19:28Z	
Elapsed Time	00s	
Run Number	5	
Is Recording Session		
Is Recording		
Last recorded file name	n/a	
Last recorded file path	n/a	
Currently recorded file name	n/a	
Currently recorded file path	n/a	
Data subdirectory path	subfolder	subfolder
File name	data_file_0016	data_file_[sc]
Root node	scan	scan
Root path	/nfs/ruche-swing/swing-soleil	
Project UID	100211	
Project GID	10021	
Project code	com-swing	
Spool project path	/nfs/srv5/spool1/tangorecorder/com-swing	
Storage destination path	/nfs/ruche-swing/swing-soleil/com-swing/subfolder	

storage/management/recordingmanager.1

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SWING storag	e/managem	-storage/recsto	rage/ma	tacq/fi	20	181386
Storage facility path Spool path Sub Directory File name	/nfs/ruche-swi /nfs/srv3/spoc 2020/Run5_Se sibiile_00002_	ing/swing-users/20181: Ing/swing-users/20181: Ing/swing-users/2018 Ing/swing-users/2018 Ing/swing-users/2018 Ing/swing-users/2018 Ing/swing-users/20181: Ing/swi	386 1386 13_15-31-19_00001	6%	Expiration: 2020 Status: Read Choose project Counters File: 1	P-11-15 08:00:00 y
Current file Root node name	sibille_00002_ ARRWT_HPLCS	HPLCSample_2020-11- ample_00002	13_15-31-19_00001.nxs	Edit	Session: 2	Reset Apply +
Acquisition name Extraction Scipt	ARRWT_HPLCS	ample IGER_to_EDF		Edit		set an counters
Last start time Recording configuration	2020-11-13T	15:31:19 elmages Big		Edit		
Last start time Recording configuration Experimental Frame	2020-11-13T I: Eiger_Multiple	15:31:19 elmages_Bio ger_{TangoRecorder	File systems monitoring	Edit Devices read errors	Recording History	Recording definitions
Last start time Recording configuration Experimental Frame 1 Timestamp 020-11-13T14:36:57.634 020 020-11-15T14:36:57.634 020 020 020-110 020 020 020 020 020 020 020 020 020	2020-11-137 Elger_Multipl RecordingManage Level 4467 INF0 4556 INF0 4551 INF0 4613 INF0 4672 INF0 4740 INF0 4725 INF0	15:31:19 elmages_Blo ger TangoRecorder Total elapsed time: Devices recording ti ans/ca/machinestatus i11-c-c03/op/mono-mt ans-c11/e1/c-u20: 00 i11-c-c02:00	File systems monitoring 005.875 mes: : 005.157 05.073 _tz.2: 005.073 s.071 _005.068	Devices read errors	Recording History	Recording definitions

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DataStorage GUI

	Red	ording Configur	ation (sur sr	v4.swing.rcl)			8
Configuration: Eiger_M	ultipleImages_Bio	• •••					н	elp
Devices Classes	Groups							
Devices	F	lecording	Pre A	cquisition		Post Acqu	isition	
KB.2-MT_R2	Z	v						-
KB.2-MT_T;	Х	V						
KB.2-MT_T	Z	v						
KB.2-STATE	ECOMPOSEF							
9 111-C-C06								
⊶ BW								
								=
ATT1_MT R	20							
	10DROINC							
FENT AL2-H	Н	r						
FENT AL2-N	MTD	Y						
FENT AL2-N	MT D VELC							
FENT_AL2-N	MT_I	V						
FENT_AL2-M	MT_I_VELO(
📑 FENT_AL2-N	MT_O	V						
📑 FENT_AL2-N	MT_O_VELC							
📑 FENT_AL2-N	MT_U	V						
FENT_AL2-N	MT_U_VELO							
Device Configuration	Class Configuration	Group Configuration	n	Attributes	Properties	Variables	5 Directives	\neg
#between " " means a val	ue			acceleration				-
'\$ (device)" : \$ (positioner),	/controller_record			accuracy				
DTISET:\$(positioner)/OTISE position:\$(positioner)/otIse	et osition			backlash				
#[pre_acg] is here a giver	n configuration			backwardLin	itSwitch			
[pre_acq]	2			deceleration	C			_
offset : \$(positioner)/offse	et			TorwardLimit	Switch			
position : \$(positioner)/pt #Inost acal is here a give	osition_\$(pre)			nosition				
[post_acq]	en configuration			positionLock	ed			
offset : \$(positioner)/offse	et			velocity				
position : \$(positioner)/po	osition_\$(post)			isAxisInitiali	zed			
Annly Annly snake case on destination data set				tuningMode				
, , , , , , , , , , ,	and case on westman			unlockReaso	nHistory			-
						Save	Save And Clo	ose

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Asynchronous process to get better performance and scalability





- This highly versatile service is now deployed on 18 beamlines and will be in production on 24 out of 29 beamlines during next spring
- Complete the writer plugin mechanism
- If another facility/institute is interested on using it, please contact us :)





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