



SOLARIS
CENTRE



SOLARIS
CENTRE

SOLARIS Status Update

Cerdanyola del Vallès, 40th Tango Community Meeting, 8–12.06.2026

Michał Piekarski, Urszula Jachymczyk, SOLARIS CSIT Team

SOLARIS National Synchrotron Radiation Centre

NSRC SOLARIS



Fot. Aleksander Koczur

NSRC SOLARIS


- Third generation light source.
- Constructed 2010 - 2015 in Krakow, Poland.
- Between 2015 and 2018 the synchrotron as well as two beamlines (PIRX and URANOS) were commissioned.
- First light in May 2016
- Since **October 2018** Solaris has been in the user operation mode.

SOLARIS research infrastructure

- Available and in user operation
- Starting up
- Under construction
- Project application accepted
- Available space for 4-5 beamlines

+

CryoEm centre





Krios

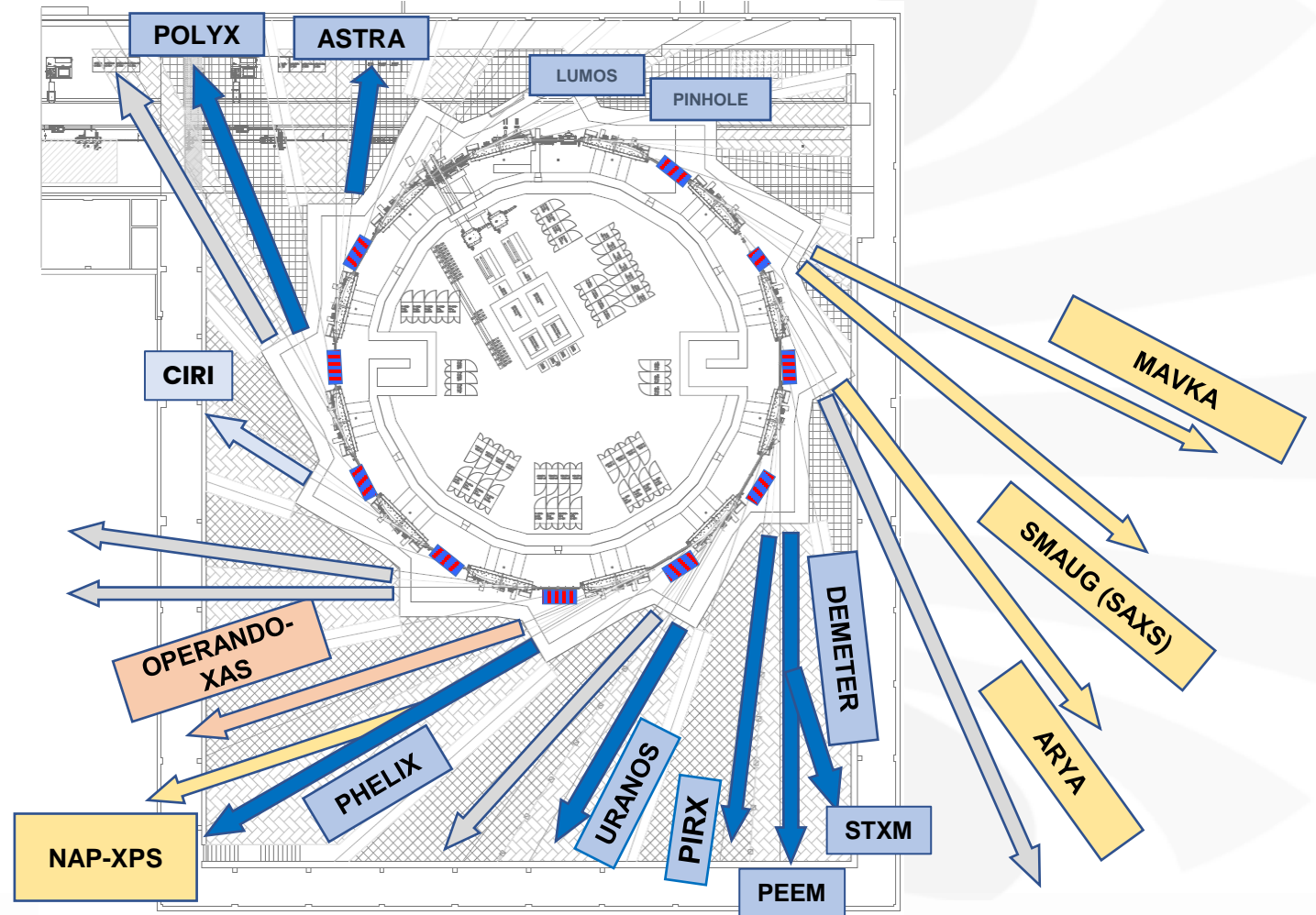
Glacios

STRUCTURAL BIOLOGY
CORE FACILITY

Neutron-lab

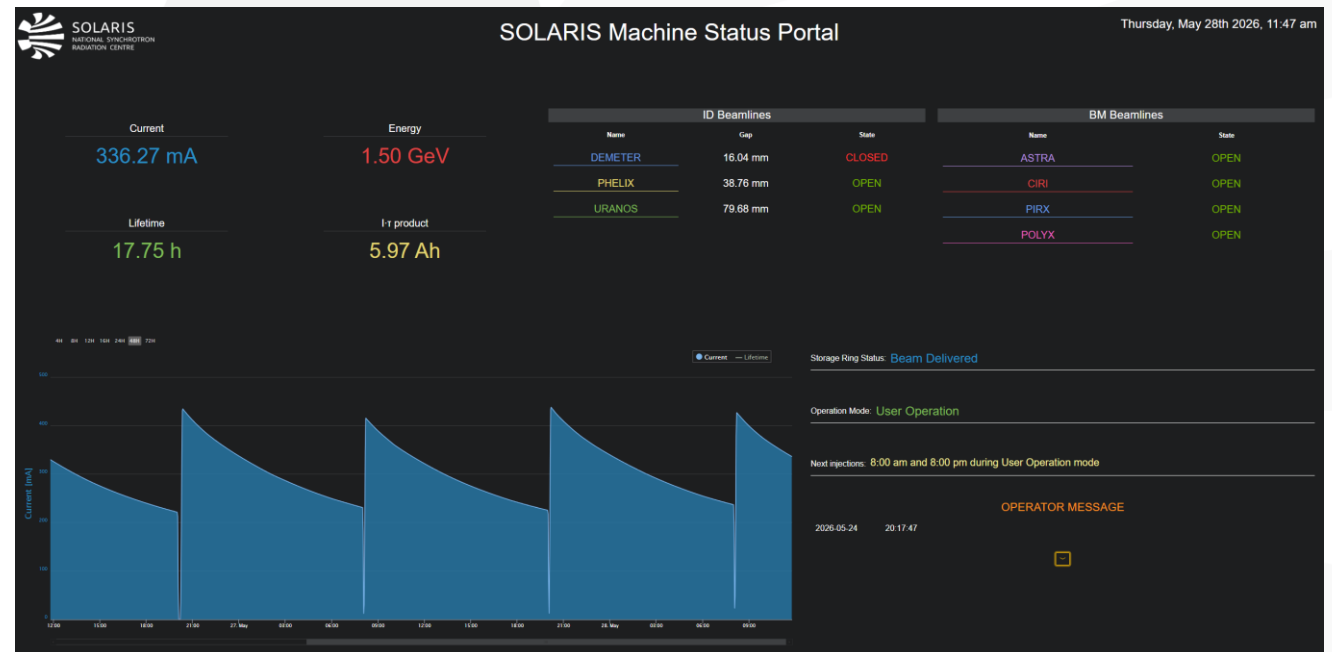



RESEARCH
UNIVERSITY
EXCELLENCE INITIATIVE
Ministry of Science
and Higher Education



SOLARIS Operation

- Operation in the decay mode
- Injection twice/day: 8:00 am and 8 pm
- Monday – machine days, maintenance
- User operation 6 days/week (Tue–Sun)
- One operation mode (uniform filling pattern)
- Single bunch operation mode under development



2026

SOLARIS CSIT Department today

- 24 people in CSIT
 - 8 Control Systems,
 - 7 IT
 - 3 pure IT/helpdesk,
 - 1 infra admin,
 - 1 cyber-security + networks,
 - 2 DevOps,
 - 7 Web-SUN / CS

Control System upgrade – achievements so far and goal for 2026

- AWX/Ansible updated to the latest version (Execution Environments) and moved to the Kubernetes cluster
- Prepared CI/CD to support two OS (el9 and el10) – for internal and external projects.
- Main Tango packages and dependencies have been built (including Tango10/pyTango10)
- All workstations in CR and on the beamlines are migrated to Alma 9
 - MATE not yet officially available for AlmaLinux10
- All of the GUIs migrated to at least Python 3.9 and Taurus 5 – even these in Python 2.7 and Taurus 3.7 version
- All VMs on the beamlines migrated to Alma9
- **GOAL: Migrate all hosts to at least Alma 9 (some already to Alma10),**
 - Summer shutdown: machine VMs migration (27 VMs, ~100 projects)
 - Alma10
 - Tango10

Control System stack in NSRC SOLARIS: summary

- OS: **Alma 9 (mainly) and 10**, Windows 10, 11 (mainly) + some embedded custom Linux
- Python versions: 3.8 (some web), **3.9 (mainly) and 3.12**
- Tango versions: **9.3.6 (mainly)**, 9.2 (embedded) -> **soon 10.3.0**
- Taurus versions: **5.1 (mainly)**, -> **soon 5.4.0**
- Sardana versions: **3.6 only** -> **soon 3.7**
- Additionally, WEB projects use Vue.js, Tango GQL and Taranta

- Cryomicroscopes are fully independent and are based on manufacturer software

SOLARIS took over Tango RPMs

tango-controls / RPM

R RPM

Recent activity

Last 30 days

Merge requests created

0

Subgroups and projects

Shared projects

Shared groups



Search (3 character minimum)



T

tango-spec

Tango spec file to build tango RPMs



O

opentelemetrycpp-spec

opentelemetry-cpp SPEC file to build RPM



fpm - packaging made simple

latest

- tricky (with build deps, toml...)
- used FPM from wheel to create RPM

Results

Source state: ✔ succeeded
Source build logs: [builder-live.log.gz](#), [backend.log.gz](#)
Built Packages: tango-common 10.3.0
tango-starter-debuginfo 9.0
tango-db-debuginfo 5.28
tango-idl 6.0.4
tango-debuginfo 10.3.0
libtango10-debuginfo 10.3.0
tango-accesscontrol 2.22
libtango10 10.3.0
tango-test 3.13
tango-debugsource 10.3.0
tango-starter 9.0
tango-universaltest-debuginfo 1.4
tango-accesscontrol-debuginfo 2.22
tango-universaltest 1.4
libtango10-devel 10.3.0
tango-admin 1.28
tango-admin-debuginfo 1.28
tango-rest-server 1.22
tango-java 10.3.0
tango-test-debuginfo 3.13
tango-db 5.28



Chroot Name	Dist Git Source	Build Time
epel-10-x86_64	b965f0d	8 minutes
epel-9-x86_64	b965f0d	8 minutes

Index of /rpm/el10/x86_64/

../		
libtango10-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	39M
libtango10-debuginfo-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	21M
libtango10-devel-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	248K
omniORB-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	2M
omniORB-debuginfo-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	6M
omniORB-debugsource-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	924K
omniORB-devel-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	2M
omniORB-devel-debuginfo-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	507K
omniORB-servers-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	58K
omniORB-servers-debuginfo-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	197K
omniORB-utils-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	58K
omniORB-utils-debuginfo-4.3.0-6.el10.x86_64.rpm	29-Apr-2026 09:04	162K
opentelemetry-cpp-1.23.0-1.el10.x86_64.rpm	29-Apr-2026 09:04	756K
opentelemetry-cpp-debuginfo-1.23.0-1.el10.x86_64.rpm	29-Apr-2026 09:04	12M
opentelemetry-cpp-debugsource-1.23.0-1.el10.x86_64.rpm	29-Apr-2026 09:04	325K
opentelemetry-cpp-devel-1.23.0-1.el10.x86_64.rpm	29-Apr-2026 09:04	424K
python3-pytango-10.1.4-1.el10.x86_64.rpm	20-Mar-2026 14:47	18M
tango-accesscontrol-2.22-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	74K
tango-accesscontrol-debuginfo-2.22-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	578K
tango-admin-1.28-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	40K
tango-admin-debuginfo-1.28-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	224K
tango-common-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	8529
tango-db-5.28-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	224K
tango-db-debuginfo-5.28-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	2M
tango-debuginfo-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	715K
tango-debugsource-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	831K
tango-idl-6.0.4-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	14K
tango-java-10.3.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	95M
tango-rest-server-1.22-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	8352
tango-starter-9.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	100K
tango-starter-debuginfo-9.0-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	816K
tango-test-3.13-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	217K
tango-test-debuginfo-3.13-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	1M
tango-universaltest-1.4-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	137K
tango-universaltest-debuginfo-1.4-28.el10.solaris.x86_64.rpm	29-Apr-2026 09:04	933K

https://pubrepo.solaris.org.pl/rpm

Some new developments

Motors Snapshots Sardana toolset

What do we have so far?

- Manages different positions profiles for motors,
- Makes snaps and saves them in dedicated catalog,

List & set profile

```
Door_lab-test_1 [6]: lsprofs
Available profiles:
[1]    FTIR
[2]    OPTIR
[3]    NANO-FTIR
```

```
Door_lab-test_1 [7]: setprof FTIR
Snap profile set to: FTIR
```

Motors Snapshots Sardana toolset

What do we have so far?

- Manages different positions profiles for motors,
- Makes snaps and saves them in dedicated catalog,
- Maintains snapshots' history for selected mode,

List & set profile

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Available profiles:
[1]    FTIR
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```

```
Door_lab-test_1 [7]: setprof FTIR
Snap profile set to: FTIR
```

Lists available snaps

```
Door_lab-test_1 [8]: lssnaps
Available snapshots for 'FTIR' profile:
[1]    000_2026_05_14_13_22_11.json
[2]    001_2026_05_25_16_29_58.json
[3]    002_2026_05_25_16_38_20.json
[4]    003_2026_05_28_14_59_38.json
```

Motors Snapshots Sardana toolset

What do we have so far?

- Manages different positions profiles for motors,
- Makes snaps and saves them in dedicated catalog,
- Maintains snapshots' history for selected mode,
- Displays data saved in snap,

Display snap file content

```
Door_lab-test_1 [13]: getsnap 2
-----
SNAP ID:      2
PROFILE:     FTIR
SNAP NAME:   002_2026_05_25_16_38_20.json
SNAP DESC:   FROM ATK_ZERO

MOTORS
=====

Rotation_L

DIAL POSITION:  0.0
POSITION:     0.0
SIGN:         1
OFFSET:       0.0
BACKLASH:     0.0
STEP PER UNIT: 111.1111111

-----

Rotation_R

DIAL POSITION:  0.0
POSITION:     0.0
SIGN:         1
OFFSET:       0.0
BACKLASH:     0.0
STEP PER UNIT: 111.1111111

-----
```

List & set profile

```
Door_lab-test_1 [6]: lsprofs
Available profiles:
[1]   FTIR
[2]   OPTIR
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```

Motors Snapshots Sardana toolset

What do we have so far?

- Manages different positions profiles for motors,
- Makes snaps and saves them in dedicated catalog,
- Maintains snapshots' history for selected mode,
- Displays data saved in snap,
- Restores motors' config from chosen snap,
- Deletes snap.

List & set profile

```
Door_lab-test_1 [6]: lsprofs
Available profiles:
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[2]    OPTIR
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Door_lab-test_1 [7]: setprof FTIR
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```

Display snap file content

```
Door_lab-test_1 [13]: getsnap 2
-----
SNAP ID:      2
PROFILE:     FTIR
SNAP NAME:   002_2026_05_25_16_38_20.json
SNAP DESC:   FROM ATK_ZERO

MOTORS
=====

Rotation_L

DIAL POSITION: 0.0
POSITION:    0.0
SIGN:        1
OFFSET:      0.0
BACKLASH:    0.0
STEP PER UNIT: 111.111111

-----

Rotation_R

DIAL POSITION: 0.0
POSITION:    0.0
SIGN:        1
OFFSET:      0.0
BACKLASH:    0.0
STEP PER UNIT: 111.111111

-----
```

Restore motors config from snap

```
Door_lab-test_1 [14]: rstsnap 2
Restoring Rotation_L...
Sign: NO CHANGE
Offset: NO CHANGE
Position: RESTORED

Restoring Rotation_R...
Sign: NO CHANGE
Offset: NO CHANGE
Position: RESTORED

DONE
```

Motors Snapshots Sardana toolset

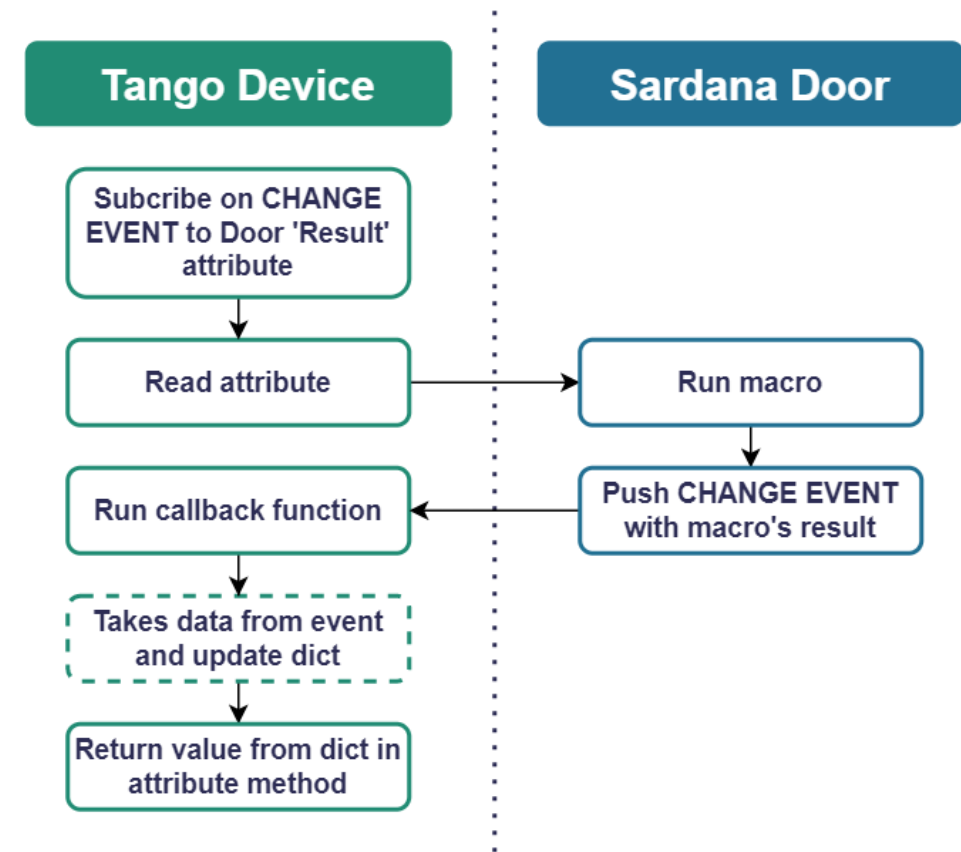
We are working on:

- Logic layer (Tango Device) which implements *Attributes* and *Commands* **based on Macro's result**,
 - Basic attributes – **DONE**
 - Basic commands – **DONE**
 - Command that takes more complex input parameters – **IN PROGRESS**
- GUI build on top of logic layer (tango device) – **IN PROGRESS**

Attribute 'snaps' - implementation example

```
@attribute(  
    dtype=(str,),  
    max_dim_x=1024,  
    access=AttrWriteType.READ,  
    label="Snapshots",  
    doc="Available snapshots for currently set profile.",  
)  
def snaps(self) -> List[str]:  
    self._run_macro("lssnaps")  
    return self._attrs_dict["snaps"]
```

Workflow details



Banana Collision

config.json

motors_proxy

axes + default
ranges

rules

- pair_range
- pair_function_range
- circle
- corridor

Banana Collision

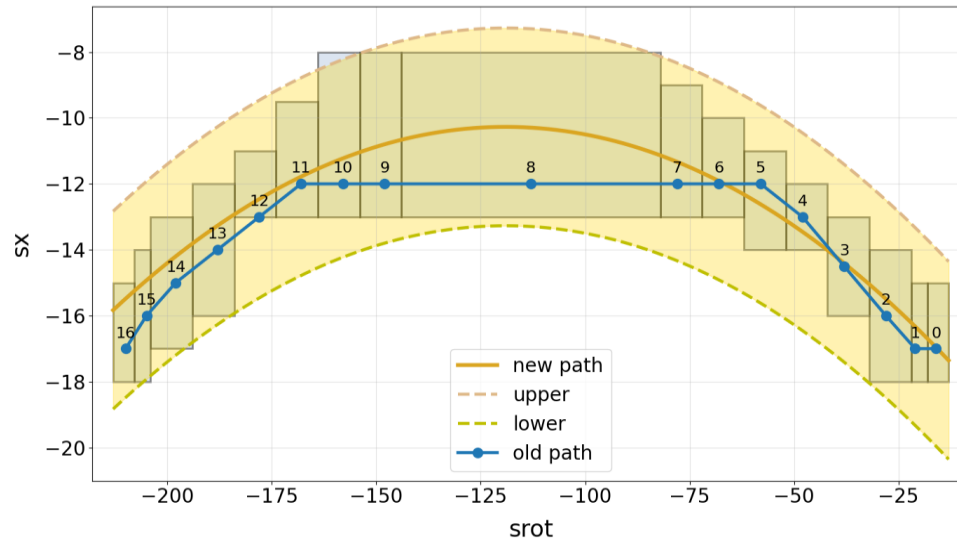
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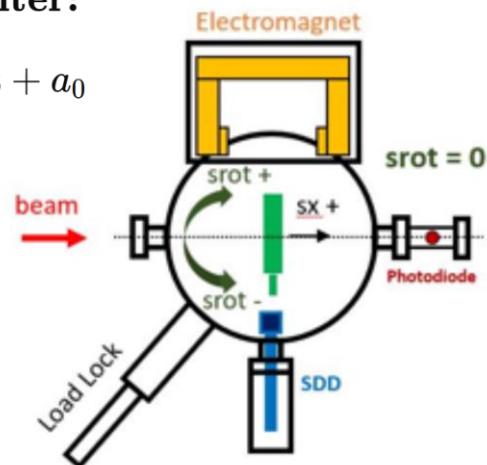


Polynomial corridor center:

$$sx_c(srot) = a_2 srot^2 + a_1 srot + a_0$$

Corridor constraint:

$$|sx - sx_c(srot)| \leq h$$



Banana Collision

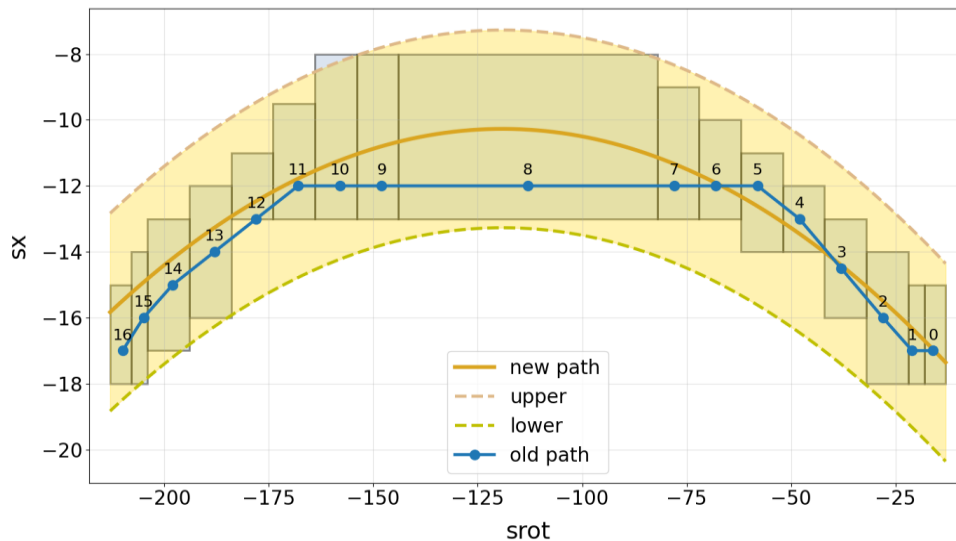
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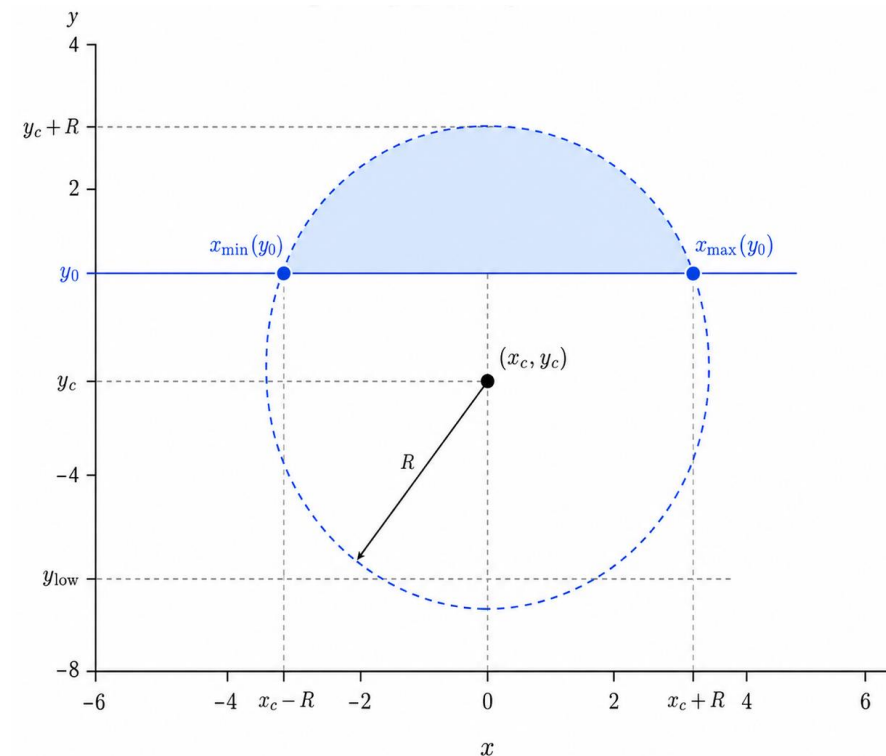
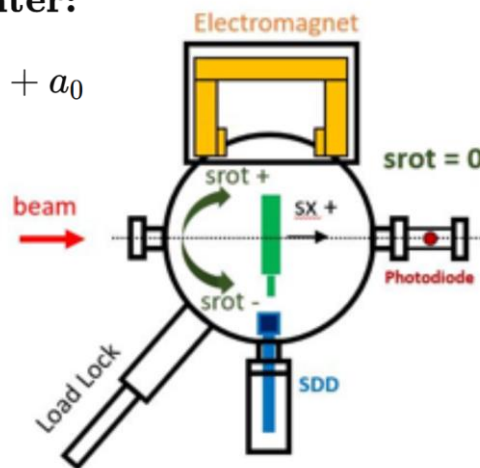


Polynomial corridor center:

$$sx_c(srot) = a_2srot^2 + a_1srot + a_0$$

Corridor constraint:

$$|sx - sx_c(srot)| \leq h$$



Circle equation:

$$(x - x_c)^2 + (y - y_c)^2 \leq R^2$$

Circle constrains:

$$x \in \left[x_c - \sqrt{R^2 - (y - y_c)^2}, x_c + \sqrt{R^2 - (y - y_c)^2} \right]$$

Banana Collision

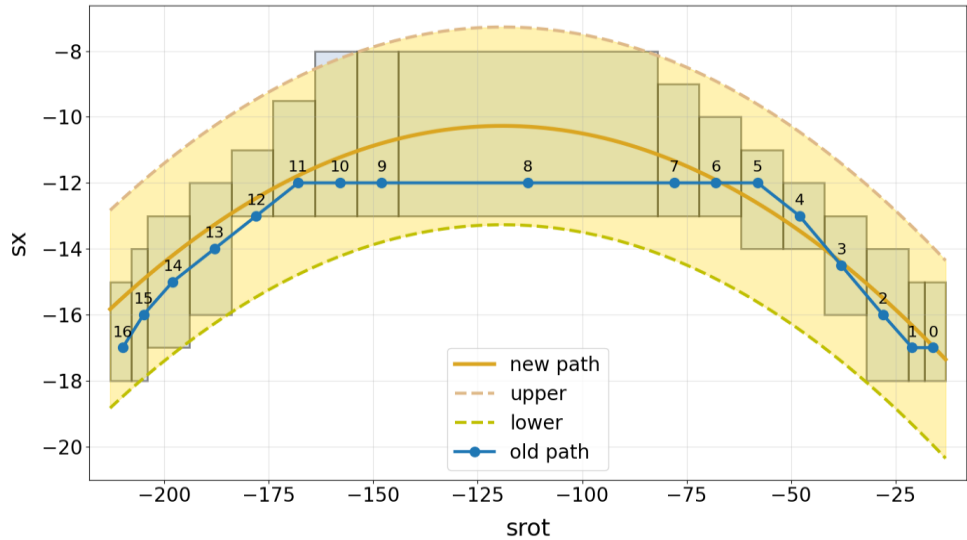
config.json

motors_proxy

axes + default ranges

rules

- pair_range
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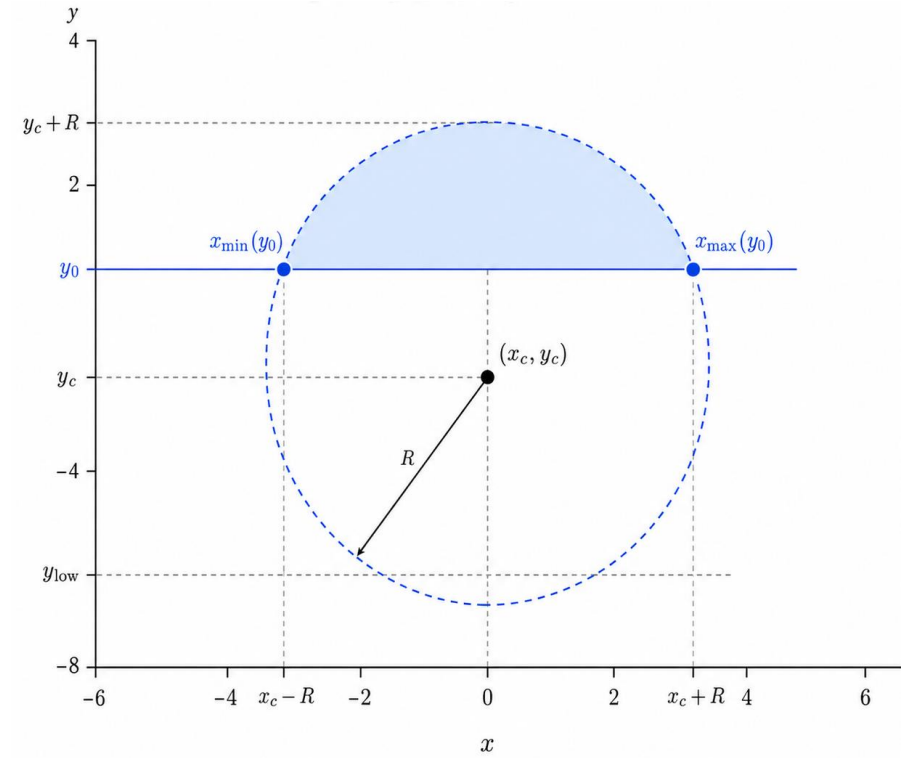
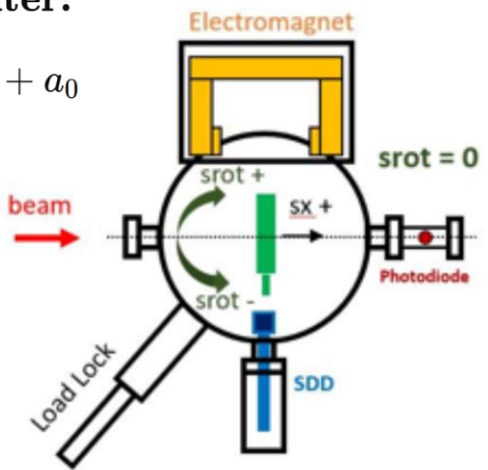


Polynomial corridor center:

$$sx_c(srot) = a_2srot^2 + a_1srot + a_0$$

Corridor constraint:

$$|sx - sx_c(srot)| \leq h$$



Circle equation:

$$(x - x_c)^2 + (y - y_c)^2 \leq R^2$$



Circle constrains:

$$x \in \left[x_c - \sqrt{R^2 - (y - y_c)^2}, x_c + \sqrt{R^2 - (y - y_c)^2} \right]$$

Function limits work both ways:

Sx ↔ **Srot**
x ↔ **y**

Automatization

- Automatic injection Logbook report
 - the report is created by filling the template with data derived from multiple DSs.
 - ~~copy + paste, manual attributes searching~~
- Automatic MSP communication after beam lost
 - After the logical value for beam dump is met, communication is shown at Machine Status Portal  informed users 

NSRC SOLARIS logbooks
SOLARIS Logbook | OPERATION PLAN | SHIFTS reports | Accelerators | Diagnostic Beamlines | Alarms

Shifts reports

Navigation: Home | Previous | Next | Find | Login | Help

Message ID: 2548 Entry time: Tue, 02 June 2026, 08:30:52

Author:	
Shift Date:	Tue, 02 June 2026, 08:30
Subject:	1st shift report

Injection without problems.

Injected **435mA** with max slope **1590uA/s**.

Cavity Voltage for ramping: 230/230 mV, for delivery: 230/230 mV.

Plungers moved at **1.1 GeV** to position: 45 / 45 mm.

SOFB - ON
FOFB - ON
RF corr - ON

Delivered **430mA** at 08:26.

Modulators switched to **STANDBY** mode.

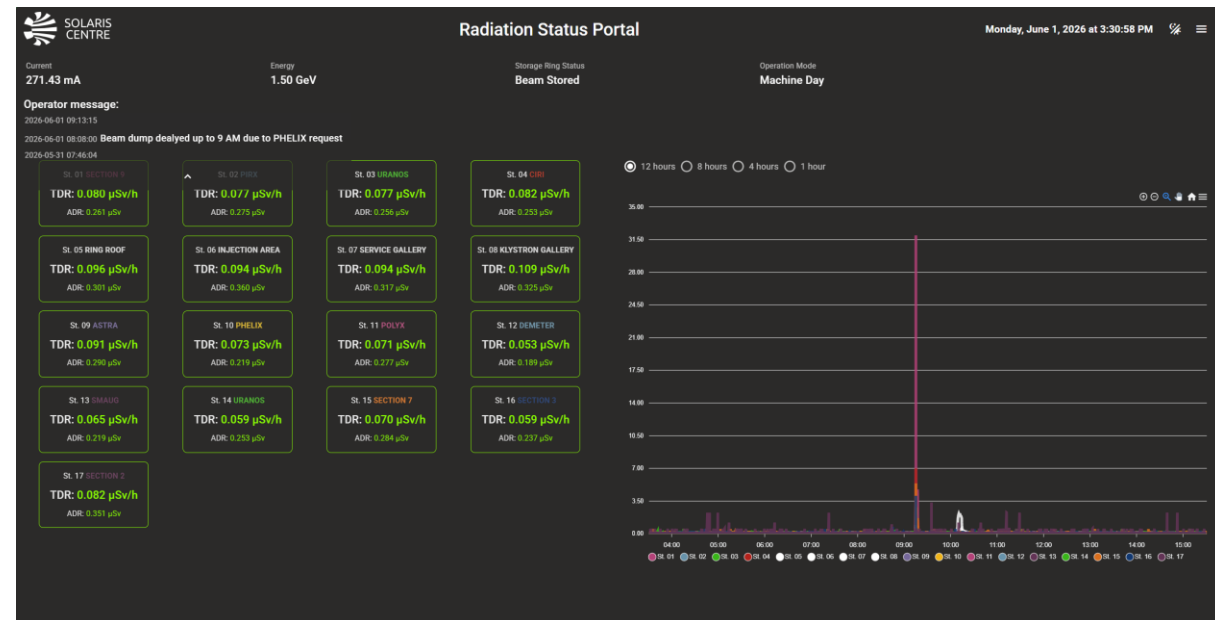
Settings for standard injection:
-->> AGC on Liberas turned ON
-->> **Below settings for copy-paste on every shift report.**
-->> In case of any changes use **bold**.

<i>MODULATOR</i>	<i>VOLTAGE</i>	<i>PHASE</i>
K00	1170	4.79
K01	1180	2.15
K02	1175	1.55
K03	1175	4.25

<i>TRANSFER LINE MAGNETS</i>	<i>CURRENT</i>
SM1AB	30.65
DIEF	37.90
<i>MASTER OSCILLATOR [RF corr]</i>	99.934768

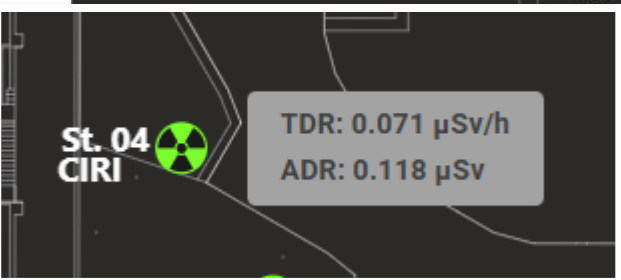
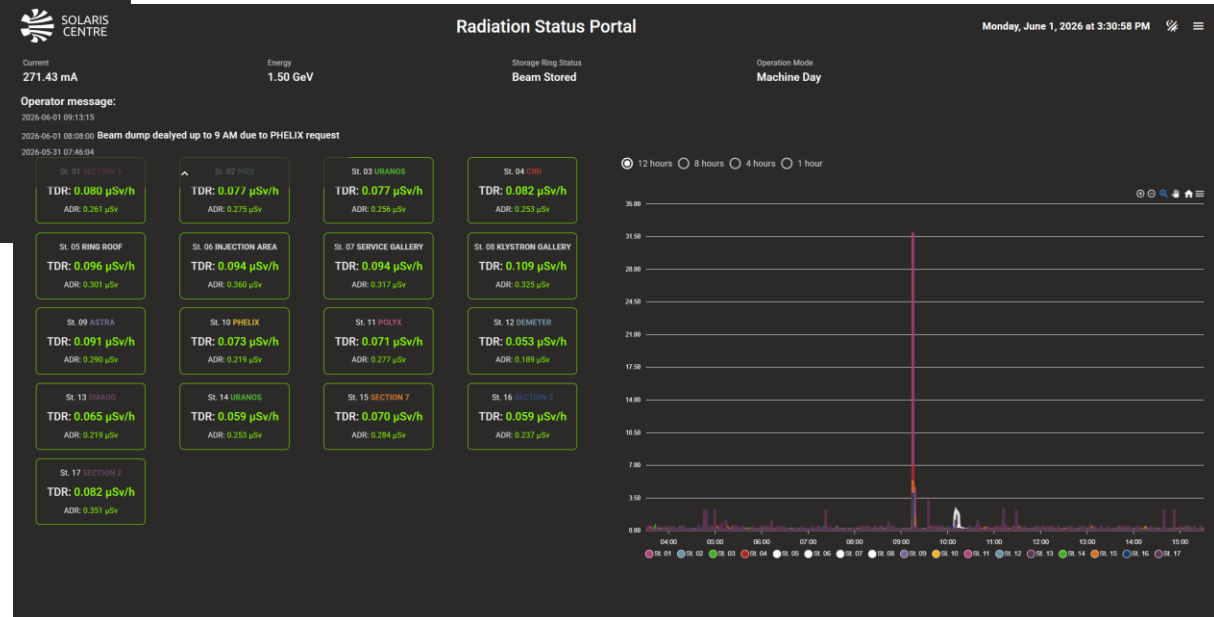
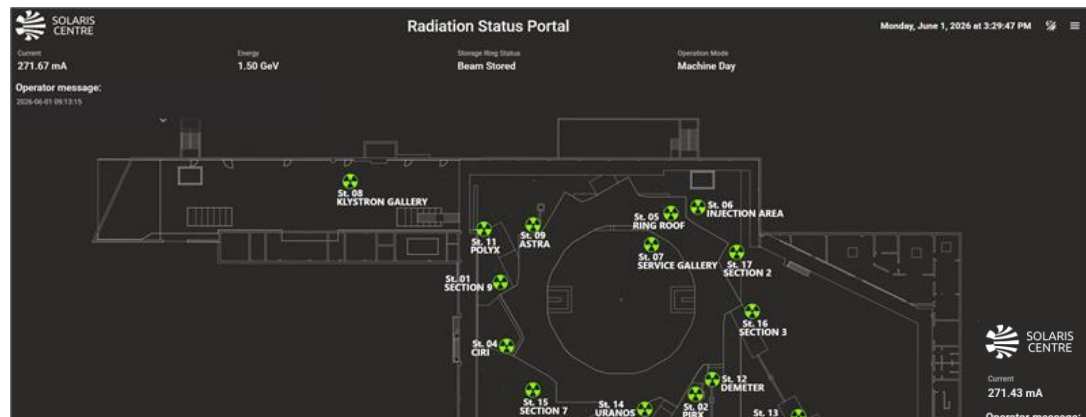
Radiation Status Portal

- Upgrade to Vue 3
- Introduce new Taranta Adriane with socket/query communication and Tango archiving for chart data



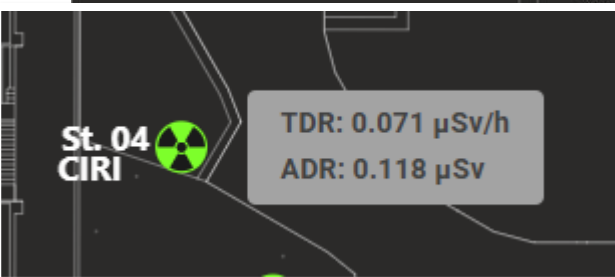
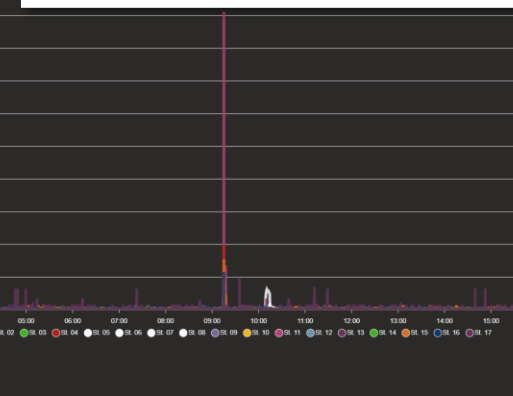
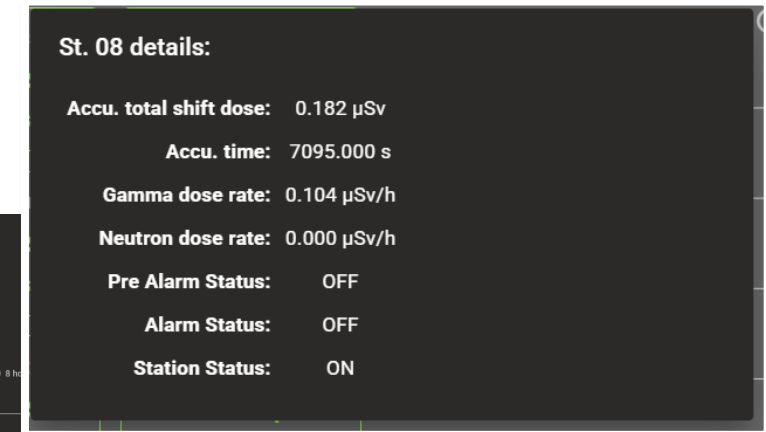
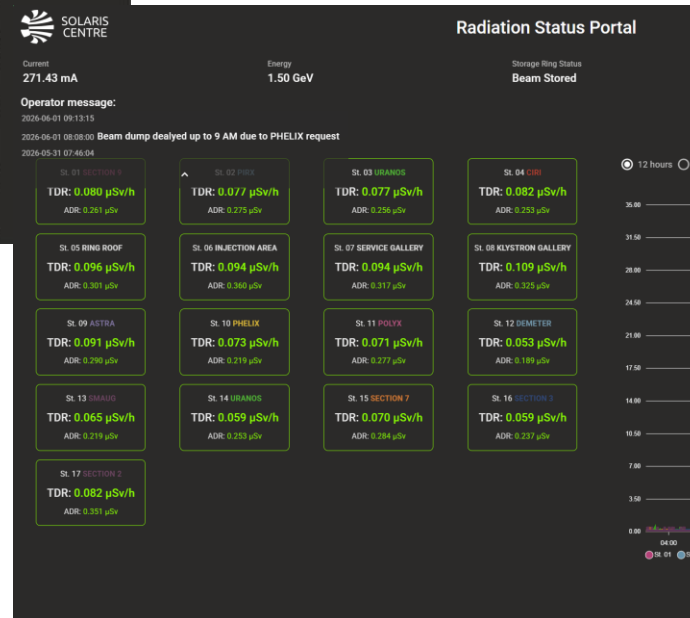
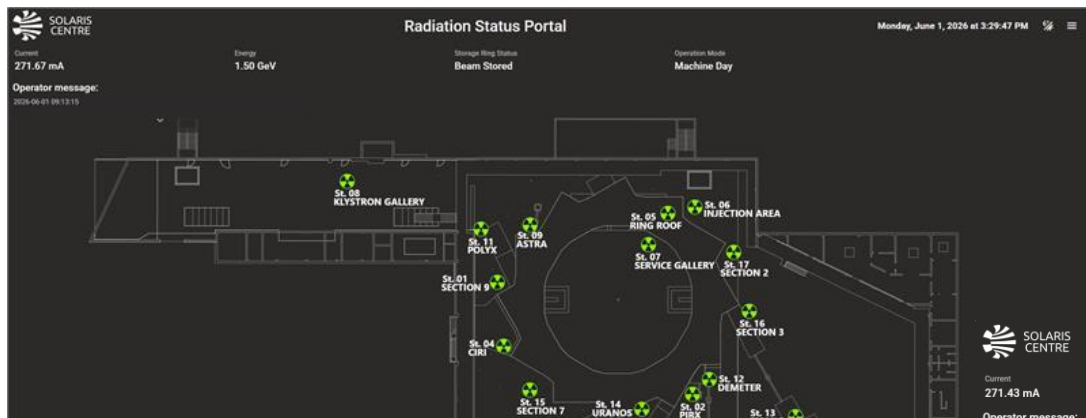
Radiation Status Portal

- Upgrade to Vue 3
- Introduce new Taranta Adriane with socket/query communication and Tango archiving for chart data
- Add a synoptic view (map-based interface) with station hover for quick value lookup



Radiation Status Portal

- Upgrade to Vue 3
- Introduce new Taranta Adriane with socket/query communication and Tango archiving for chart data
- Add a synoptic view (map-based interface) with station hover for quick value lookup
- Enable dialog display with more station's attributes (by clicking on stations or on a station card in the status view)





Thank you!

Questions?